# OSCILLATION CRITERION FOR SOME DIFFERENTIAL EQUATION OF SECOND ORDER WITH INTEGRABLE COEFICIENTS 

Fatima N. Ahmed ${ }^{1}$, Souad A. Abumaryam ${ }^{2}$, Anis I. Saad ${ }^{3}$<br>${ }^{1}$ Department of Mathematics, College of Education, University of Sirte/Libya, zahra8072@su.edu.ly<br>${ }^{2}$ Department of Mathematics, College of Science, University of Sirte/Libya, s.ahmed@su.edu.ly<br>${ }^{3}$ Department of Mathematics, College of Science, University of Omar Al-Mukhtar/ Libya, Anis.saad@omu.edu.ly


#### Abstract

In this presented paper, we are concerned with the oscillatory behaviour of solutions of some nonlinear ordinary differential equations of second order. Primarily, we are interested in the study of equations with integrable coefficients. By using the Riccati substitution technique, many open problems are discussed and some new sufficient conditions for the oscillation are obtained. Some applications of the obtained results are also provided to show the feasibility of the new results.


Keywords: Oscillation; Nonlinear differential equations; Second Order; Integrable Coefficients.
الملخص
في هذه الورقة، نهتم بسلوك التذبذب لحلول بعض المعادلات التفاضلية العادية غير الخطية من الرتبة الثانية، تحديدا
المعادلات ذات المعامالات القابلة للتكامل حيث تمت مناقشة عدد من القضايا باستخدام تعويض ريكاتي وتم الحصول على
عدد من الشـروط الكافية للتذبذب. تم تزويد البحث ببعض التطبيقات للنتائج المتحصل عليها لبيـان جدوى النتائج الجـديدة.
الكلمات المفتاحية : التذبذب، المعادلات التفاضلية غير الخطية، الرتبة الثانية، معاملات قابلة للتكامل.

[^0]1. INTRODUCTIOIn physical and engineering problems, questions related to the oscillation theory play an important role. As a result, there has been much activity concerning with oscillatory and asymptotic behavior of many different classes of differential equations, see for example [1,3-10] and the references cited therein. This paper deals with the problem of the oscillation of all solutions of the following second order nonlinear differential equation

$$
\begin{equation*}
(r(t) \dot{x}(t))^{*}+q(t)|x(t)|^{\gamma} \operatorname{sign} x(t)=0, \quad t \geq t_{0} \tag{1}
\end{equation*}
$$

where $q$ and $r$ are continuous functions on the interval $\left[t_{0}, \infty\right), t_{0} \geq t, r(t)$ is a positive function on the real line $\Re$ and $\gamma>0$. Our attention here is concentrated only to such solution $x(t)$ of the differential equation (1) which exists on some interval $\left[t_{0}, \infty\right), t_{0} \geq 0$.

Definition 1. A solution $x(t)$ of the differential equation (1) is said to be nontrivial if $x(t) \neq 0$ for at least one $t$ in the interval $\left[t_{0}, \infty\right), t_{0} \geq 0$.

Definition 2. A nontrivial solution $x(t)$ of the differential equation (1) is said to be oscillatory if it has arbitrarily large zeros on $\left[t_{0}, \infty\right), t_{0} \geq 0$, otherwise, it is said to be nonoscillatory.

Definition 3. Equation (1) is called oscillatory if all of its solutions are oscillatory, otherwise, it is said to be nonoscillatory.

Recently, Ahmed and Ali [2] provided some new criteria for the oscillation of equation (1) and their results are for the sublinear case, that is, for $0<\gamma<1$, and their results are not applicable to equation (1) with $\gamma>0$. Also, one can see the papers of Elabbasy and Elzeiny [5], Grace and Lalli [7], Philos [13] and Yeh [16]. However, the main purpose of this paper is to establish some new criteria for the oscillation of equation (1) for the superlinear case, that is, for $\gamma>1$, by using an averaging condition of the type introduced by Kamenev [8]. Therefore, results obtained here can be considered as a continuation of the work done by Ahmed and Ali [2]. As a contribution to this study we refer to the papers of Grace [6], Yeh [16] and Saad et al. [14].

## 2. MAIN RESULTS

In this section we state and prove some results of the oscillation of the equation (1). Some examples are also listed here to show the evidence of our own results.

## Theorem 1

Suppose that
( $\mathrm{O}_{1}$ ) $0<A \leq \mathrm{r}(t) \leq B, t \geq 0$, and $A, B \in R$
$\left(\mathrm{O}_{2}\right) \quad \dot{r}(t)>0, t \geq 0$,
( $\mathrm{O}_{3}$ ) $\liminf _{t \rightarrow \infty} \int_{t_{0}}^{t} q(s) d s \geq-\lambda>-\infty ; \lambda>0$,
( $\mathrm{O}_{4}$ ) $\quad \lim _{t \rightarrow \infty} \sup \frac{1}{t} \int_{t_{0}}^{t} \int_{t_{0}}^{s} q(u) d u d s=\infty$.
Then the equation (1) is oscillatory when $\gamma>1$.

Proof : Assume the contrary ; then there exists a solution $x(t)$ which may be assumed to be positive on $\left[T_{1}, \infty\right)$ for some $T_{1} \geq t_{0}$. Dividing (1) through by $x^{\gamma}(t)$ and integrating from $T_{1}$ to $t$, we obtain that

$$
\begin{equation*}
\frac{r(t) x^{x}(t)}{x^{Y}(t)}+\gamma \int_{T_{1}}^{t} \frac{r(s) x^{2}(s)}{x^{Y}} d s+\int_{T_{1}}^{t} q(s) d s=C, \quad C=\frac{r\left(T_{1}\right) x\left(T_{1}\right)}{x^{Y}\left(T_{1}\right)} \tag{2}
\end{equation*}
$$

Now, from the condition $\left(\mathrm{O}_{1}\right)$, since $A \leq r(t)$, then we have from (2),

$$
\begin{equation*}
\frac{r(t) x^{(t)}}{x^{\gamma}(t)}+\gamma A \int_{T_{1}}^{t}\left(\frac{x^{2}(s)}{x^{\beta}(s)}\right)^{2} d s+\int_{T_{1}}^{t} q(s) d s \leq C, \quad \beta=\frac{(\gamma+1)}{2} \tag{3}
\end{equation*}
$$

Integrating (3) once more from $\mathrm{T}_{1}$ to t we obtain

$$
\begin{equation*}
\int_{T_{1}}^{t} r(s) \frac{x(s)}{x^{\gamma}(s)} d s+\gamma A \int_{T_{1}}^{t} \int_{T_{1}}^{s}\left(\frac{x^{x}(u)}{x^{\beta}(u)}\right)^{2} d u d s+\int_{T_{1}}^{t} \int_{T_{1}}^{s} q(u) d u d s \leq C\left(t-T_{1}\right) \tag{4}
\end{equation*}
$$

For the first integral of (4), we have from the condition $\left(\mathrm{O}_{2}\right)$ that $r(t)$ is a non-decreasing on $t \geq T_{1} \geq t_{0}$. So, by the Bonnet's theorem there exists $T_{2} \in\left[T_{1}, t\right]$ such that

$$
\int_{T_{1}}^{t} \frac{r(s) \dot{x}(s)}{x^{\gamma}(s)} d s=r(t) \int_{T_{2}}^{t} \frac{\dot{x}(s)}{x^{\gamma}(s)} d s=\frac{r(t)}{(1-\gamma)}\left[x^{-\gamma+1}(t)-x^{-\gamma+1}\left(T_{2}\right)\right]
$$

By substituting in (4) we obtain that

$$
\begin{equation*}
\frac{r(t) x^{1-\gamma}(t)}{1-\gamma}+\gamma A \int_{T_{1} T_{1}}^{t} \int_{x}^{s}\left(x(u) / x^{\beta}(u)\right)^{2} d u d s+\int_{T_{1} T_{1}}^{t} \int^{s} q(u) d u d s \leq C\left(t-T_{1}\right)+\frac{r(t) x^{1-\gamma}\left(T_{2}\right)}{1-\gamma} \tag{5}
\end{equation*}
$$

Since $0<r(t) \leq B$ and $\quad \gamma>1$. Then, by the assumption that $x(t)>0$, we have

$$
\frac{r(t) x^{1-\gamma}(t)}{1-\gamma} \geq \frac{B x^{1-\gamma}(t)}{1-\gamma} \text { and } \quad \frac{r(t) x^{1-\gamma}\left(T_{2}\right)}{1-\gamma}<0 .
$$

Hence (5) becomes

$$
\begin{equation*}
\frac{\beta}{(1-\gamma)} x^{1-\gamma}(t)+\gamma A \int_{T_{1}}^{t} \int_{T_{1}}^{s}\left(\frac{x(u)}{x^{\beta}(u)}\right)^{2} d u d s+\int_{T_{1}}^{t} \int_{T_{1}}^{s} q(u) d u d s \leq C\left(t-T_{1}\right) \tag{6}
\end{equation*}
$$

We distinguish three cases of the behaviour of $\dot{x}(t)$, namely,
(i) $\dot{x}(t)$ oscillatory on $\left[T_{1}, \infty\right)$,
(ii) $\dot{x}(t)>0 \quad$ on $\left[T_{3}, \infty\right)$ for some $T_{3} \geq T_{1}$,
(iii) $\dot{x}(t)<0$ on $\left[T_{3}, \infty\right)$ for some $T_{3} \geq T_{1}$,
and show that the assumption $x(t)>0$ leads to a contradiction in each case. Suppose that $\dot{x}(t)$ oscillatory, then there exists a sequence $\left\{t_{n}, n=1,2, \ldots\right\}$ in $\left[T_{1}, \infty\right)$ such that

$$
\dot{x}\left(t_{n}\right)=0 \quad \text { and } \quad t_{n} \rightarrow \infty \text { as } n \rightarrow \infty .
$$

Oscillation Criterion for Some Differential Equations of Second Order with Integrable Coefficients
It follows from the inequality (3) and condition $\left(\mathrm{O}_{3}\right)$ that

$$
\int_{T_{1}}^{\infty}\left(\dot{x}(s) / x^{\beta}(s)\right)^{2} d s \leq \frac{C_{3}+\lambda}{\gamma A}<\infty
$$

and then $\dot{x}(t) x^{-\beta}(t) \in L^{2}\left(T_{1}, \infty\right)$, which means that there exists a constant $M_{0}>0$ such that

$$
\int_{T_{1}}^{t}\left(\dot{x(s)} / x_{x^{\beta}(s)}\right)^{2} d s \leq M_{0}
$$

Then by Schwarz's inequality we note that

$$
\begin{aligned}
\left|\int_{T_{1}}^{t} \dot{x(s)} / x_{x^{\beta}(s)} d s\right|^{2} & \leq\left(\int_{T_{1}}^{t} d s\right)\left(\int_{T_{1}}^{t}\left({ }_{x}^{\dot{x}(s)} / x_{x^{\beta}(s)}\right)^{2} d s\right) \\
& \leq t \int_{T_{1}}^{t}\left(\dot{x}(s) / x^{\beta}(s)\right)^{2} d s \\
& \leq M_{0} t
\end{aligned}
$$

thus, for all $t \geq T_{1}$, we have

$$
-\sqrt{M_{0} t} \leq \frac{1}{1-\beta}\left(x^{1-\beta}(t)-x^{1-\beta}\left(T_{1}\right)\right) \leq \sqrt{M_{0} t}
$$

Since $1-\beta={ }^{(1-\gamma)} / 2<0$. Then we obtain

$$
\begin{aligned}
x^{1-\beta}\left(T_{1}\right)+(\beta-1) \sqrt{M_{0} t} \geq x^{1-\beta}(t) & \geq(1-\beta) \sqrt{M_{0} t}+x^{1-\beta}\left(T_{1}\right) \\
& \geq(1-\beta) \sqrt{M_{0} t}-x^{1-\beta}\left(T_{1}\right)
\end{aligned}
$$

which implies that

$$
\begin{equation*}
x^{1-\gamma}(t) \leq\left(x^{1-\beta}\left(T_{1}\right)+(\beta-1) \sqrt{M_{0} t}\right)^{2} \tag{*}
\end{equation*}
$$

On the other hand since $2(\beta-1)=\gamma-1$ and $\gamma>1$ then we have

$$
4(\beta-1)^{2}=\gamma^{2}-2 \gamma+1<2 \gamma(\gamma-1)
$$

so we obtain

$$
\begin{equation*}
\frac{1}{(\beta-1)^{2}}>\frac{1}{2(\beta-1)^{2}}>\frac{1}{\gamma(\gamma-1)} \tag{**}
\end{equation*}
$$

Now, inequalities $\left({ }^{*}\right)$ and $\left({ }^{* *}\right)$ give us the following inequality is valid

$$
-\frac{x^{-\gamma+1}(t)}{\gamma(\gamma-1)}>-\left[\frac{x^{1-\beta}\left(T_{1}\right)+(\beta-1) \sqrt{M_{0} t}}{\beta-1}\right]^{2}
$$

Hence from (6) we obtain, for all $t \geq T_{1}$, that

$$
\begin{equation*}
-\gamma B\left[\frac{x^{1-\beta}\left(T_{1}\right)+(\beta-1) \sqrt{M_{0}} t}{\beta-1}\right]^{2}+\int_{T_{1} T_{1}}^{t} \int_{1}^{s} q(u) d u d s \leq C_{3}\left(t-T_{1}\right) \tag{7}
\end{equation*}
$$

Dividing (7) by $t$ and taking the upper limit as $t \rightarrow \infty$, we obtain

$$
\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{T_{1} T_{1}}^{t} \int_{1}^{s} q(u) d u d s<\infty,
$$

which is a contradiction to the condition $\left(\mathrm{O}_{4}\right)$. Next, suppose that $\dot{x}(t)>0$ for $t \geq T_{3} \geq T_{1}$. Thus

$$
x(t) \geq x\left(T_{3}\right) \text { and } x^{-\gamma+1}(t) \leq x^{-\gamma+1}\left(T_{3}\right) .
$$

We deduce from (6) that

$$
\begin{equation*}
\frac{\beta}{(1-\gamma)} x^{1-\gamma}\left(T_{3}\right)+\int_{T_{1}}^{t} \int_{T_{1}}^{s} q(u) d u d s \leq C\left(t-T_{1}\right) \tag{8}
\end{equation*}
$$

Dividing (8) by t and taking the upper limit as $t \rightarrow \infty$, we obtain

$$
\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{T_{1} T_{1}}^{t} \int^{s} q(u) d u d s<\infty,
$$

which again contradicts the condition (7). Finally, we assume that $\dot{x}(t)<0$ for $t \geq T_{3} \geq T_{1}$.
By condition $\left(\mathrm{O}_{3}\right)$, we can estimate (3) as follows,

$$
\begin{equation*}
-\frac{r(t) \dot{x}(t)}{x^{\gamma}(t)} \geq-\left(C_{3}+\lambda\right)+\gamma A \int_{T_{1}}^{t}\left(\frac{\dot{x}(s)}{x^{\beta}(s)}\right)^{2} d s \tag{9}
\end{equation*}
$$

Since $r(t) \leq B \quad$ and $\dot{x}(t)<0$. Then $-\frac{r(t) \dot{x}(t)}{x^{\gamma}(t)} \leq-\frac{\dot{B} \dot{x}(t)}{x^{\gamma}(t)}$, substituting in (9), we obtain

$$
\begin{equation*}
-\frac{\dot{x}(t)}{x^{\gamma}(t)} \geq-k+\gamma \frac{A}{B} \int_{T_{1}}^{t}\left(\dot{x}(s) / x^{\beta}(s)\right)^{2} d s \tag{10}
\end{equation*}
$$

where

$$
k=\left(C_{3}+\lambda\right) / B \text { and } \gamma \frac{A}{B} \int_{T_{1}}^{T_{3}}\left(\dot{x}(s) / x^{\beta}(s)\right)^{2} d s \geq 0
$$

If the integral in (10) is finite as $t \rightarrow \infty$, we can deduce a contradiction as a similar way as the case when $x(t)$ is oscillatory. Otherwise we may choose $T \geq T_{3}$ such that

$$
\begin{equation*}
\gamma \frac{A}{B} \int_{T_{3}}^{T} \frac{\stackrel{\bullet 2}{x}(s)}{x^{\gamma+1}(s)} d s=1+k \tag{11}
\end{equation*}
$$

for $t \geq T$, we multiply (10) through by

$$
-\dot{x}(t) / x(t) /\left\{-k+\frac{\gamma A}{B} \int_{T_{3}}^{t}\left(\dot{x}(s) / x^{\beta}(s)\right)^{2} d s\right\}
$$

$\qquad$ and integrating from $T$ to $t$ as follows

$$
\begin{equation*}
\int_{T}^{t}\left[\stackrel{\bullet 2}{x}(s) / x^{\gamma+1}(s) /\left\{-k+\frac{\gamma A}{B} \int_{T_{3}}^{s}\left(\dot{x}(u) / x^{\beta}(u)\right)^{2} d u\right\}\right] d s \geq \int_{T}^{t}-\frac{\dot{x}(s)}{x(s)} d s \tag{12}
\end{equation*}
$$

For the integral in L.H.S. of (12), since

$$
\begin{aligned}
\frac{d}{d s}\left[-k+\frac{\gamma A}{B} \int_{T_{3}}^{s} \frac{\bullet 2}{x^{\gamma+1}(u)} d u\right] & =\frac{\gamma A}{B} \times \frac{d}{d s}\left(\int_{T_{3}}^{s} \frac{\bullet \cdot 2}{x^{\gamma+1}(u)} d u\right) \\
& =\gamma \frac{A}{B} \times \frac{\cdot x(s)}{x^{\gamma+1}(s)} \times 1
\end{aligned}
$$

Therefore, we obtain that

Using (13) in the inequality (12), we obtain

$$
\ln \left\{-k+\frac{\gamma A}{B} \int_{T_{3}}^{t} \frac{\bullet \cdot x(s)}{x^{\gamma+1}(s)} d s\right\} \geq \frac{\gamma A}{B} \ln \frac{x(T)}{x(t)}=\ln \left[\frac{x(T)}{x(t)}\right]^{\frac{\gamma A}{B}}
$$

this together with (10) yields $-\frac{\dot{x}(t)}{x^{\gamma}(t)} \geq \frac{x^{\frac{\gamma A}{B}}(T)}{x^{\frac{\gamma A}{B}}(t)}$, which implies that $-\dot{x}(t) \geq x^{\frac{\gamma A}{B}}(T) x^{\gamma\left(1-\frac{A}{B}\right)}(t)$
so, we have

$$
\begin{equation*}
\dot{x}(t) \leq-x^{\frac{\gamma A}{B}}(T) x^{\gamma\left(1-\frac{A}{B}\right)}(t) \tag{14}
\end{equation*}
$$

But we have $0<A \leq B$, this implies that $1-\frac{A}{B} \geq 0$. Also, since $x(t)>0$. This means that there exists a constant $\theta$ such that $x(t) \geq \theta>0$. Then we have from (14) that

$$
\dot{x}(t) \leq-x^{\frac{\gamma A}{B}}(T) \theta^{\gamma\left(1-\frac{A}{B}\right)}=-M^{\prime}, M^{\prime}>0
$$

Therefore $x(t) \leq-M^{\prime}\left(t-T_{1}\right)+x\left(T_{1}\right)$, which implies that $x(t) \rightarrow-\infty$ as $t \rightarrow \infty$. But this contradicts the assumption that $x(t)>0$. This completes the proof.

Example 1. Consider the following differential equation

$$
\begin{equation*}
((1+t /(t+1)) \dot{x}(t))^{\cdot}+\left(t-e^{t}\right)|x(t)|^{\gamma} \operatorname{sign} x(t)=0, \quad t \geq t_{0} \geq 0,1<\gamma . \tag{15}
\end{equation*}
$$

Note that
(i) $1 \leq r(t)=1+\frac{t}{t+1}<2$,
(ii) $\dot{r}(t)=\frac{1}{(t+1)^{2}}>0 \quad$ for all $t \geq 0$
(iii) $\liminf _{t \rightarrow \infty} \int_{t_{0}}^{t} q(s) d s=\liminf _{t \rightarrow \infty} \int_{t_{0}}^{t}\left[s-e^{s}\right] d s$

$$
\begin{aligned}
& =\liminf _{t \rightarrow \infty}\left[\frac{s^{2}}{2}-\left.e^{s}\right|_{t_{0}} ^{t}\right. \\
& =\liminf _{t \rightarrow \infty}\left[\frac{t^{2}}{2}-e^{t}-\frac{t_{0}{ }^{2}}{2}+e^{t_{0}}\right] \\
& =\infty>-\lambda>-\infty ; \lambda>0,
\end{aligned}
$$

(iiii) $\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{t_{0}}^{t} \int_{t_{0}}^{s} q(u) d u d s=\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{t_{0}}^{t}\left[\frac{s^{2}}{2}-e^{s}-\frac{t_{0}{ }^{2}}{2}+e^{t_{0}}\right] d s$

$$
\begin{aligned}
& =\limsup _{t \rightarrow \infty} \frac{1}{t}\left[\frac{t^{3}}{6}-e^{t}-\frac{t_{0}^{2}}{2} t+t e^{t_{0}}\right. \\
& \left.-\frac{t_{0}^{3}}{6}+e^{t_{0}}+\frac{t_{0}^{3}}{2}-t_{0} e^{t_{0}}\right] \\
& =\infty .
\end{aligned}
$$

Hence, by the Theorem 1, we conclude that the given equation is oscillatory for all $\gamma>1$
$\qquad$

## Theorem 2:

Suppose that $\left(\mathrm{O}_{1}\right)$ and $\left(\mathrm{O}_{3}\right),\left(\mathrm{O}_{4}\right)$ hold and suppose in addition that

$$
\text { (O5) } \quad \dot{r}(t) \leq 0 \quad \text { for } \quad t \geq t_{0}
$$

Then the equation (1) is oscillatory when $\gamma>1$.

Proof: Assume the contrary, then there exists a solution $x(t)$ which may be assumed to be positive on $\left[T_{1}, \infty\right)$ for some $T_{1} \geq t_{0} \geq 0$. As in the proof of Theorem 1 , we obtain the inequality (4), that is

$$
\begin{equation*}
\int_{T_{1}}^{t} \frac{r(s) \dot{x}(s)}{x^{\gamma}(s)} d s+\gamma A \int_{T_{1} T_{1}}^{t} \int_{( }^{s}\left(\dot{x}(u) / x^{\beta}(u)\right)^{2} d u d s+\int_{T_{1} T_{1}}^{t} \int_{1}^{s} q(u) d u d s \leq C_{3}\left(t-T_{1}\right) \tag{4}
\end{equation*}
$$

Now, for the first integral of (4), we have by condition $\left(\mathrm{O}_{5}\right)$ that $r(t)$ is non increasing on $\left[T_{1}, \infty\right)$.So , by the Bonnet theorem there exists $a_{t} \in\left[T_{1}, t\right]$ such that

$$
\int_{T_{1}}^{t} r(s) \frac{\dot{x}(s)}{x^{\gamma}(s)} d s=r\left(T_{1}\right) \int_{T_{1}}^{a_{1}} \frac{\dot{x}(s)}{x^{\gamma}(s)} d s=\frac{r\left(T_{1}\right)}{1-\gamma}\left[x^{-\gamma+1}\left(a_{t}\right)-x^{-\gamma+1}\left(T_{1}\right)\right]
$$

By substituting in (4), we obtain

$$
\begin{align*}
\frac{r\left(T_{1}\right) x^{1-\gamma}\left(a_{t}\right)}{1-\gamma}+\gamma A \int_{T_{1} T_{1}}^{t} \int_{1}^{s}\left(\dot{x}(u) / x^{\beta}(u)\right)^{2} d u d s+\int_{T_{1} T_{1}}^{t} \int_{1}^{s} q(u) d u d s & \\
& \leq C_{3}\left(t-T_{1}\right)+\frac{r\left(T_{1}\right) x^{1-\gamma}\left(T_{1}\right)}{1-\gamma} \\
& \leq C_{3}\left(t-T_{1}\right) \tag{16}
\end{align*}
$$

Since $r\left(T_{1}\right) \leq B$. Then $\frac{r\left(T_{1}\right) x^{1-\gamma}\left(a_{t}\right)}{1-\gamma} \geq \frac{B x^{1-\gamma}\left(a_{t}\right)}{1-\gamma}$. So from (16) we have

$$
\frac{B x^{1-\gamma}\left(a_{t}\right)}{1-\gamma}+\gamma A \int_{T_{1} T_{1}}^{t} \int_{T_{1}}^{s}\left(\dot{x}(u) / x_{x^{\beta}(u)}\right)^{2} d u d s+\int_{T_{1} T_{1}}^{t} \int_{1}^{s} q(u) d u d s \leq C_{3}\left(t-T_{1}\right)
$$

then the rest of the proof is similar that of the proof of Theorem 2 and then it will be omitted.

## Example 2

$$
\begin{equation*}
[(e+1 /(t+1)) \dot{x}(t)]^{\cdot}+\left(\frac{t}{5}+\sin t\right)|x(t)|^{\gamma} \operatorname{signx}(t)=0, \quad t \geq t_{0} \geq 0,1<\gamma \tag{17}
\end{equation*}
$$

## Note that

(i) $e<r(t)=e+1 /(t+1)<e+1$
(ii) $\dot{r}(t)=-\frac{1}{(t+1)^{2}}<0$ forall $t \geq 0$,
(iii) $\liminf _{t \rightarrow \infty} \int_{t_{0}}^{t} q(s) d s=\liminf _{t \rightarrow \infty} \int_{t_{0}}^{t}\left(\frac{s}{5}+\sin s\right) d s$

$$
\begin{aligned}
& =\liminf _{t \rightarrow \infty}\left[\frac{t^{2}}{10}-\cos t-\frac{t_{0}{ }^{2}}{10}+\cos t_{0}\right] \\
& =\infty>-\lambda>-\infty ; \lambda>0,
\end{aligned}
$$

(iiii) $\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{t_{0}}^{t} \int_{t_{0}}^{s} q(u) d u d s=\limsup _{t \rightarrow \infty} \frac{1}{t} \int_{t_{0}}^{t}\left[\frac{s^{2}}{10}-\cos s-\frac{t_{0}{ }^{2}}{10}+\cos t_{0}\right] d s$

$$
\begin{aligned}
&=\lim _{t \rightarrow \infty} \sup \frac{1}{t}-\left[\frac{t^{3}}{30}-\sin t-\frac{t_{0}{ }^{2}}{10} t+t \cos t_{0}\right. \\
&-\frac{t_{0}{ }^{3}}{30}+\sin t_{0}+\frac{t_{0}{ }^{3}}{10}-t_{0} \cos t_{0}=\infty
\end{aligned}
$$

Hence, by the Theorem 2, we conclude that the given equation is oscillatory for all $\gamma>1$

## Remark

Theorems 1 and 2 are extended for the results of Nasr [11], Onose [12] and Wong [15].

## 3.CONCLUSIONS

In a conclusion, we study the oscillation behavior for some nonlinear differential equations. However, we obtained some sufficient conditions for all the solutions to be oscillate. Our results extend and/or generalize some previous theorems in the literature. Some examples are also given to illustrate the new results.

## REFERENCES

[1] Ahmed, F. N., Ahmad, R. R., Din, U. S., Noorani, M. S, (2018), Some open problems in the theory for neutral delay differential equations, Scientific Journal of Applied Sciences, Sirte University, Libya, 8, 12-18.
[2] Ahmed, F. N., Ali, D. A., (2019), On the oscillation property for some nonlinear differential equations of second order, Journal of Pure \& Applied Sciences, Sebha University, Libya, Vol. 18,342-345.
[3] Bartle, R.G. The elements of real analysis, 7th ed., John Wiley and Sons, 233, 1976.
[4] Butler, G. J., (1980), Integral averages and the oscillation of second order ordinary differential equations, SIAM J. Math. Anal. 11, 190-200.
[5] Elabbasy, E. M., and Elzeiny; Sh. R., (2011), Oscillation theorems concerning non-linear differential equations of the second order, Opuscula Mathematica, 31, 373-391.

Oscillation Criterion for Some Differential Equations of Second Order with Integrable Coefficients
[6] Grace, S.R., (1992), Oscillation theorems for nonlinear differential equations of second order, J. Math. Anal. Appl. 171, 220-240.
[7] Grace, S. R., and Lalli; B. S., (1990), Integral averaging technique for the oscillation of second order nonlinear differential equations. J. Math. Anal. Appl. 149, 277-311.
[8] Kamenev, I.V., (1978), Integral criterion for oscillation of linear differential equations of second order, Math. Zametki, 23, 249-251.
[9] Kim, R.J. (2011), Oscillation criteria of differential equations of second order, Korean J. Math., 19, No. 3, 309-319.
[10] Li; H. J. (1995), Oscillation criteria for second order linear differential equations, J. Math. Anal. Appl. 194, 217-234.
[11] Nasr, A. H., (1998), Sufficient conditions for the oscillation of forced super-linear second order differential equations with oscillatory potential, Amer. Math. Soc. 126,123-125
[12] Onose, H., (1975), Oscillations criteria for second order nonlinear differential equations, Proc. Amer. Math. Soc. 51, 67-73.
[13] Philos; Ch. G., (1989), Oscillation theorems for linear differential equations of second order, Arch. Math. 53, 483-492.
[14] Saad M. J., Salhin A. A. and Ahmed F. N., (2021). Oscillatory behaviour of second order nonlinear differential equations. International Journal of Multidisciplinary Sciences and Advanced Technology. 565-571.
[15] Wong, J. S. W., (1986), An oscillation criterion for second order nonlinear differential equations, Proc. Amer. Math. Soc. 98, 109-112.
[16] Yeh; C. C., (1982), Oscillation theorems for nonlinear second order differential equations with damping terms. Proc. Amer. Math. Sac. 84, 397-402.


[^0]:    Author Correspondent: zahra8072@su.edu.ly

